Article

A Force Balance Can Explain Local and Global Cell Movements during Early Zebrafish Development

Jack Chai,¹ Andrea L. Hamilton,² Michael Krieg,² Craig D. Buckley,¹ Ingmar H. Riedel-Kruse,³ and Alexander R. Dunn^{1,4,*}

¹Department of Chemical Engineering, Stanford University, Stanford, California; ²Department of Molecular and Cellular Physiology, Stanford University School of Medicine, Stanford, California; ³Department of Bioengineering, Stanford University, Stanford, California; and ⁴Stanford Cardiovascular Institute, Stanford University School of Medicine, Stanford, California, Stanford, California; and ⁴Stanford Cardiovascular Institute, Stanford University School of Medicine, Stanford, California, Stanford, California; Stan

ABSTRACT Embryonic morphogenesis takes place via a series of dramatic collective cell movements. The mechanisms that coordinate these intricate structural transformations across an entire organism are not well understood. In this study, we used gentle mechanical deformation of developing zebrafish embryos to probe the role of physical forces in generating long-range intercellular coordination during epiboly, the process in which the blastoderm spreads over the yolk cell. Geometric distortion of the embryo resulted in nonuniform blastoderm migration and realignment of the anterior-posterior (AP) axis, as defined by the locations at which the head and tail form, toward the new long axis of the embryo and away from the initial animal-vegetal axis defined by the starting location of the blastoderm. We found that local alterations in the rate of blastoderm migration correlated with the local geometry of the embryo. Chemical disruption of the contractile ring of actin and myosin immediately vegetal to the blastoderm margin via Ca²⁺ reduction or treatment with blebbistatin restored uniform migration and eliminated AP axis reorientation in mechanically deformed embryos; it also resulted in cellular disorganization at the blastoderm margin. Our results support a model in which tension generated by the contractile actomyosin ring coordinates epiboly on both the organismal and cellular scales. Our observations likewise suggest that the AP axis is distinct from the initial animal-vegetal axis in zebrafish.

INTRODUCTION

Robust morphogenetic patterning during embryonic development requires control of cell movements over distances much larger than individual cells (1,2). Although cells in culture exhibit collective migration in some circumstances (3), they do not exhibit the exquisite long-range coordination commonly observed during development. This and other observations imply that cues intrinsic to intact organisms are essential in driving morphogenetic patterning.

In this study, we use zebrafish embryos as a model system to investigate the mechanisms by which mechanical cues coordinate morphogenetic movements. In zebrafish, the first observable large-scale cell movement occurs during epiboly, when the blastoderm spreads across the yolk cell from the animal pole to the vegetal pole (Fig. 1 *A*) (4). During this process, cell migration is coordinated across the entire length of the blastoderm margin (~3 mm at 50% epiboly). How the cells at the blastoderm margin coordinate migration over such a large distance is, to our knowledge, not understood.

The actin band, a contractile ring of actin and myosin, assembles immediately vegetal to the blastoderm margin,

Editor: Rong Li. © 2015 The Authors 0006-3495/15/07/0407/8 \$2.00 and generates a contractile force termed cable constriction tension (CCT) (Fig. 1 A) (5–8). It is important to note that similar contractile actomyosin bands are observed across many biological processes, for example, during epithelial wound healing (9,10) and dorsal closure in Drosophila (11–13). Until recently, a prevailing hypothesis concerning the role of these analogous actomyosin structures was that they drive blastoderm migration (zebrafish), dorsal closure (Drosophila), and epithelial wound contraction by constricting the cell sheet in a purse-string-like fashion (8). However, recent observations have prompted a reevaluation of this model. Laser cutting of the actin band does not slow the rate of dorsal closure in Drosophila (12). Further, zebrafish embryos that are physically constrained to adopt a cylindrical shape successfully complete epiboly even though the force from CCT cannot contribute to the progress of epiboly in this geometry (5). Thus, at present, the function of the actin band and CCT during these processes is unclear.

In zebrafish, the role of CCT in development has been difficult to determine, in part because the embryo is normally symmetric about the animal-vegetal (AV) axis, resulting in uniform CCT along the blastoderm margin. We used gentle mechanical compression in the form of an agarose overlay to alter the shape of the embryo (Fig. 1 B). This manipulation removes the initial symmetry about the AV axis, allowing an imbalance of forces to emerge. We then

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FIGURE 1 Mechanical deformation probes the role of CCT in zebrafish epiboly. (A) (i) Schematic representation of epiboly. The blastoderm mass (green) begins at the animal pole of the yolk (yellow). Over time the blastoderm spreads over the yolk (ii (50% epiboly)) until it converges at the vegetal pole (iii). An actomyosin contractile band (red) forms just vegetal of the blastoderm margin. (B) Schematic depiction of directional compression, showing 1.4% w/v agarose (dark blue) and 0.8% w/v lowmelting-point agarose (light blue). (i and ii) Agarose overlays are applied directionally to generate a shear direction. (iii) Embryos mounted in agarose are initially symmetric. (iv) Addition of an agarose overlay gently compresses the embryos, causing them to become asymmetric and introducing a new long axis at an angle relative to the AV axis. The shear direction in (iv) is rotated 90° into the page from (i) and (ii). Scale bar, 250 μ m.

imaged cells along the blastoderm margin to examine the role of CCT in coordinating the migration of neighboring cells. As discussed below, disruption of CCT leads to striking changes in blastoderm migration on both the cellular and global length scales. A quantitative physical model based on force balance within the embryo accounts for these observations and suggests that CCT acts to coordinate cell movement during epiboly.

MATERIALS AND METHODS

Preparation of media varying in Ca²⁺ concentrations

A 20× stock of E2 buffer was prepared by mixing 300 mM NaCl (BP358-212, Fisher Scientific, Pittsburgh, PA), 10 mM KCl (P217-500), 20 mM CaCl₂ (C79-500, Fisher), 20 mM MgSO₄ (194833, MP Biomedicals, Burlingame, CA), 3 mM KH₂PO₄ (BP362-500, Fisher), 1 mM Na₂HPO₄ (PB 332-500 Fisher) and adjusting the pH to 7.0 using HCl. A calcium-free stock of $20 \times E2$ buffer was made by mixing the salts mentioned above without CaCl₂ and adjusting the pH to 7.0 using NaOH. Media of differing final Ca^{2+} concentrations were achieved by mixing the two stocks at varying ratios.

Zebrafish embryo preparation

All embryos used in these experiments were obtained by mating either TL wildtype zebrafish embryos or Tg(actb2:Hsa.MAP7-EGFP)hm1 zebrafish (14). Embryos were harvested 30 min postfertilization and dechorionated using pronase. Briefly, embryos were placed in a 1 mg/mL solution of pronase (P6911-5G, Sigma Aldrich, St. Louis, MO) in Hanks balanced salt solution (HBSS) (14025, Life Technologies, South San Francisco, CA) for 1-5 min until the chorions spontaneously detached from the embryo. The embryos were then transferred to a solution of 16 mM EDTA (15576-028, Invitrogen, Grand Island, NY) in HBSS for 2 min to quench the pronase. Quenching was followed by washing the embryos in a solution of HBSS for 2 min. Following chorion removal, embryos were washed in the corresponding media (E2 \pm Ca²⁺ \pm blebbistatin (1852, R&D Systems, Minneapolis, MN)) three times and then mounted in 0.8% low-meltingpoint agarose. In compression experiments, an additional agarose overlay (3 mL of 1.4% agarose made in 35 mm glass-bottom dishes the previous night) was applied on top of the solidified mounting agarose to provide compression (Fig. 1). Time-lapse bright-field images of the embryos were taken every 4-8 min over the course of 24 h using a Nikon Ti-E inverted microscope maintained at 28°C. Embryos grown in 62.5 $\mu M~Ca^{2+}$ media exhibit ~8% mortality in the first 24 h of development (4/50). Embryos grown in the presence of blebbistatin have ~80% mortality in the first 24 h of development (41/50).

Fixing and staining of zebrafish embryos

Embryos were grown until the desired time point and fixed overnight with 4% paraformaldehyde at 4°C. After fixing, embryos were washed three times in PBS at 5 min intervals, followed by two washes in PBS + 0.1% Tween (PBST) at 5 min intervals. A final wash was conducted in PBST + 1% dimethylsulfoxide (PBSTD) for 5 min. The embryos were then placed into a blocking solution of 10% bovine serum albumin in PBSTD for 2 h at room temperature. After blocking, the embryos were labeled with 1 μ g/mL tetramethylrhodamine (TMR)-phalloidin for 1 h at room temperature in the dark, then washed extensively (at least six times) in a solution of 1% bovine serum albumin in PBSTD. The fixed and stained embryos were imaged using a spinning-disk confocal on a Nikon Ti-E or a point-scanning confocal on a Leica SP5 in the Stanford Cell Sciences Imaging Facility.

Image analysis

All calculations of rates and angles in zebrafish were performed on embryos post invagination to ensure that calculated velocities are not affected by the momentary pause in epiboly during invagination. We observe that invagination occurs at ~30% epiboly in compressed embryos. Our analysis thus makes use of data recorded in embryos at between 30% and 80% epiboly. Movies were initially processed in Fiji (15) to enhance the contrast between the blastula and the yolk. In addition, a Canny-Deriche edge detection algorithm was applied to generate an image that outlines the boundary of the entire embryo (Fig. S1 in the Supporting Material). Subsequent data analysis was performed using MATLAB. The tangent vector of each point along the boundary of the embryo was calculated by taking the numerical derivative over 25 points neighboring the point. During epiboly, approximate locations of the blastoderm edges were tracked at 8- to 10-min intervals by manual selection. A more accurate blastoderm edge location was then calculated by finding the nearest point in the boundary image to the manually selected point. Migration rates were then determined by dividing the distance that the blastoderm traveled along the edge of the embryo by the time between each measurement.

The $\cos\theta$ term used (see below, Eqs. 1–4) was calculated by taking the dot product of the tangent vector, as defined above, with the magnitude of the vector normalized to unity, with the normalized cable constriction vector determined by the line connecting the left and right edges of the blastoderm margin. Finally, the rate of epiboly was calculated by finding the arc length between the current and previous edges of the blastoderm margin and dividing by the time between the two points.

MATLAB modeling and simulations

For the 2D simulations, we used the binary edge image found using the Canny-Deriche algorithm (described above and shown in Fig. S1) to set the geometry of the embryo. The left and right edges of the blastoderm provided the initial starting locations for the blastoderm margin. In the 3D models, we used an ellipsoid geometry, as described in the Supporting Material, with an initial blastoderm location found by cutting a plane through the ellipsoid to form the initial ring. To perform the simulation, we tracked the movement of 100 points along the ring during their simulated migration across the surface of the ellipsoidal embryo. In both 2D and 3D simulations, we performed a Monte Carlo simulation performed in MATLAB with the basal tangential rate of epiboly set at 40 nm/s, except in the high blebbistatin case in which epiboly was set at 22 nm/s to mirror the slowing of epiboly observed experimentally. For MATLAB models of epiboly that incorporated CCT, we set the contribution of CCT at the experimentally determined value of 28 nm/s. For each step of the Monte Carlo simulation in both 2D and 3D, we calculated how much each edge moved during the step, and advanced that distance along the edge of the binary edge image. After each step, the tangential and CCT vectors were recalculated at the new locations. In models of embryos in which CCT was perturbed to mirror epiboly in embryos grown in reduced calcium media or blebbistatin, we set the CCT contribution to 0 nm/s.

Tracking the roughness of the margin

Confocal stacks recorded for TMR-phalloidin-stained embryos were flattened using a maximum intensity projection. The boundaries of the cells on the margin were manually tracked and a cell center was calculated by finding the center of the boundary of the cells (Fig. S2). These centers were used to calculate the vectors between neighboring cells.

RESULTS

Epiboly does not progress uniformly in asymmetric embryos

We first tested the role of CCT by removing the symmetry of embryos about the AV axis. We accomplished this by gently shearing dechorionated embryos via directional compression using an agarose overlay (Fig. 1 B). In these asymmetric embryos, we observe that the blastoderm mass, and consequently the initial AV axis, lies at an angle relative to the new long axis of the embryo. The blastoderm remains in this off-axis position throughout cell division and the mid-blastula transition (MBT) (Fig. 2, A and B). After MBT, the edges of the blastoderm progress at different velocities throughout epiboly. We observe that the trailing edge migrates faster, and thus traverses a greater distance, than the leading edge (Fig. 2, C-E, and Movie S1). As a result, the blastoderm margin rotates toward an alignment perpendicular to the long axis of the embryo (Fig. 2, E and F). In contrast, blastoderm margin migration progresses



FIGURE 2 Development of a compressed embryo from the four-cell stage to the conclusion of epiboly shows alterations in the local rate of epiboly and reorientation of the embryonic AP axis. (A-F) Compressed embryo in the four-cell stage (A), immediately after the MBT (B), at 30% epiboly (C), at 70% epiboly (D), and immediately after blastopore closure (E). The trailing, right edge migrates farther than the leading, left edge. Red triangles indicate the initial AV axis orientation and blue triangles the AP axis. (F) Light blue lines connect the left and right edges of the blastoderm margin at successive time points. Faster migration along the right side of the embryo causes the center of the blastoderm margin (dark blue line) to rotate relative to the initial AV axis (black dashed line). (G-I) Uncompressed embryo at the one-cell stage (G), at 50% epiboly (H; note that both edges have progressed equal distances at this time), and immediately after blastopore closure (I). Red triangles represent the initial AV axis and blue triangles the AP axis at the conclusion of epiboly. Note that in the uncompressed embryos, the AV and AP axes are aligned. Scale bar, 250 µm. (See also Movie S1.)

uniformly in uncompressed embryos (Fig. 2, *G–I*). These results suggest that mechanical compression breaks the symmetry of the embryo and alters the rates of epiboly unequally along the edges of the blastoderm.

Differences in velocity and force depend upon local shape

We observe blastoderm reorientation in compressed embryos of diverse shapes, indicating that this observation is unlikely to reflect a specific embryo geometry (Fig. S3). Instead, it is likely that blastoderm reorientation reflects an imbalance of forces at the blastoderm margin. Previous studies identified two major forces during blastoderm migration: CCT, which is directed toward the center of the actin ring; and a tangential component, which is directed along the surface of the embryo and generated by a combination of flow friction (5), microtubule dynamics (16–18), blastula retraction (19), and/or other processes (20,21). We define an asymmetry factor, $\Delta \cos \theta$, which is the difference in the cosines of the tangent and CCT vectors on the two edges of the embryos ($\cos\theta_L$ and $\cos\theta_R$; Fig. 3 A). In an unperturbed, symmetric embryo, $\Delta \cos\theta$ is close to zero. In shape-perturbed embryos, $\Delta \cos \theta$ provides a simple metric for how much the shape is changed. A plot of the difference in blastoderm migration rates on the left and right sides of the compressed embryos (Δv) versus $\Delta \cos\theta$ reveals a positive linear correlation (Fig. 3 C). Although there is significant variability in the data due to variations in the mounting agarose, variations in the orientation at which the zebrafish embryo lies relative to the imaging plane (ideally, the anterior-posterior (AP) axis forms perpendicularly to the imaging plane for this experiment), or innate differences between the individual embryos, a general trend emerges in which higher Δv and $\Delta \cos\theta$ are correlated (Fig. 3 C). This observation suggests that an imbalance of local forces emerges from imposed shape asymmetries, which in turn leads to different migration velocities at the leading and lagging edges of the blastoderm margin. The slope of a linear fit to the data in Fig. 3 C yields a value



FIGURE 3 Differential BM migration can be quantified via a simple force balance. (A) The free body diagram of forces at each edge of the blastoderm margin. Red arrows indicate a constant driving tangential force, F_{Tan} . Blue arrows indicate the force generated by CCT. The vectors F_{Tan} and F_{CCT} form the angle θ . (See also Fig. S4 and Movies S2 and S3.) (B) The projection of F_{CCT} (blue arrows) adds to F_{Tan} on the right edge and counteracts F_{Tan} on the left edge, creating a larger net force at the right edge of the blastoderm margin (purple arrows). (C) Experimental data shown in blue are Δv and $\Delta \cos\theta$ calculated at 30 min intervals between 30% and 80% epiboly in 16 embryos. A seven-point moving average is shown in green to indicate the overall trend. A linear fit of Δv versus $\Delta \cos\theta$ is shown in red ($R^2 -$ 0.12), which yields a slope of 23 ± 6 nm s⁻¹ (p-value < 0.001 equivalent to 0 nm s⁻¹) and intercept of 0.30 ± 1.56 nm s⁻¹, with uncertainties determined based on the least-squares fit of the raw data (blue) to a line (red). E2(+): E2 medium including 1 mM Ca²⁺.

of 23 \pm 6 nm s⁻¹. This value gives a measure of how fast reorientation occurs. Importantly, it is the same order of magnitude as the rate of epiboly (40 \pm 4 nm s⁻¹; mean \pm SE), as determined from the rates of epiboly measured across 16 embryos grown in normal E2 media.

Force-balance models recapitulate blastoderm reorientation in asymmetric embryos

We developed both two-dimensional (2D) and three-dimensional (3D) models of blastoderm migration on an asymmetric yolk (Fig. 3, A and B, Supporting Material, Figs. S4 and S5, and Movies S2 and S3). Since both models generate essentially the same results, we present the 2D model here because it is more concise. As mentioned previously, there are two main forces present during epiboly, a tangential force along the surface of the embryo, F_{Tan} , and the force resulting from CCT, F_{CCT} , which is directed toward the geometric center of the actin band. The net force on the edge of the blastoderm margin, F_{Net} , can be related to an observed cell migration velocity, v, by introducing a drag coefficient, c_{Drag}, that arises from cell-cell, cell-yolk, and in our case blastoderm-agarose interactions (22-24). In 2D, a simple relationship relates F_{CCT} and F_{Tan} to the migration velocity observed on the left and right sides of the embryo as seen in cross section (Fig. 3 *B*):

$$F_{\text{Net,right}} = c_{\text{Drag}} v_{\text{right}} = F_{\text{Tan,right}} + F_{\text{CCT}} \cos\theta_{\text{R}} \quad (1)$$

$$F_{\text{Net,left}} = c_{\text{Drag}} v_{\text{left}} = F_{\text{Tan,left}} + F_{\text{CCT}} \cos\theta_{\text{L}}.$$
 (2)

These equations predict that Δv , the difference in velocities of the leading and lagging edges of the blastoderm margin, is

$$F_{\text{Net,right}} - F_{\text{Net,left}} = c_{\text{Drag}} (v_{\text{right}} - v_{\text{left}})$$
$$= (F_{\text{Tan,right}} - F_{\text{Tan,left}})$$
$$+ F_{\text{CCT}} (\cos\theta_{\text{R}} - \cos\theta_{\text{L}}) \qquad (3)$$

$$\Delta v = \frac{\Delta F_{\text{Tan}}}{c_{\text{Drag}}} + \frac{F_{\text{CCT}}\Delta\cos\theta}{c_{\text{Drag}}}.$$
 (4)

In unperturbed, symmetric embryos ($\Delta \cos\theta = 0$), the blastoderm margin spreads uniformly ($\Delta v = 0$), suggesting that the tangential force is also uniform ($\Delta F_{Tan} = 0$). In principle, the nonzero Δv in shape-perturbed embryos could result from differences in local force production ($\Delta F_{Tan} \neq 0$) resulting from some form of biochemical feedback. However, as will be shown, the more parsimonious assumption that $\Delta F_{Tan} = 0$ in both unperturbed and compressed embryos is sufficient to account for the data. Under the simplifying assumption that the F_{Tan} is uniform along the embryo, equation 4 simplifies to:

$$\Delta v = \frac{F_{\rm CCT} \Delta \cos\theta}{c_{\rm Drag}}.$$
 (5)

Importantly, equation 5 reproduces the linear relationship between Δv and $\Delta \cos\theta$ observed for a wide variety of embryo shapes (Fig. 3). The physical interpretation is that CCT provides a supplemental force that is sensitive to local asymmetries in the embryo, and that speeds up the lagging edge of the embryo while simultaneously slowing down the leading edge. As a result, the blastoderm reorients toward the imposed long axis. Equation 5 also predicts that the blastoderm in symmetric embryos should spread uniformly (Δv and $\Delta \cos\theta = 0$), as is in fact observed. The unconstrained linear fit for $\Delta v vs$. $\Delta \cos \theta$ returns an intercept value that was close to zero (Table S1), consistent with the idea that a simple force balance is sufficient to account for the rate of blastoderm migration in both unperturbed and asymmetric embryos.

Chemical disruption of CCT leads to uniform blastoderm margin migration velocity

A consequence of our model (Equation 5) is the prediction that abrogating CCT should prevent reorientation. Previous studies show that altering Ca^{2+} concentration in the surrounding media provides an effective mechanism to modulate CCT: the actin band does not form when Ca^{2+} is sequestered from the embryo growth media by EGTA or BAPTA (7), while increased extracellular Ca^{2+} results in an oblong embryo phenotype consistent with increased actin band contractility (8). Importantly, we observe that development proceeds normally through 16 h (completion of epiboly), at all of the Ca^{2+} concentrations greater than or equal to 62.5 μ M, demonstrating that Ca^{2+} reduction is a suitable method for targeted disruption of CCT.

We find that blastoderm reorientation does not occur in reduced, 62.5 μ M Ca²⁺ media ($\Delta v \approx 0$), regardless of embryo geometry (Figs. 4 and S6). Moreover, the overall rate of epiboly of embryos grown in reduced Ca²⁺ media is not statistically different from that observed in E2 media, indicating that the F_{Tan} is essentially unaltered under these conditions (Fig. S4 *B*). These results could, in principle, imply that changes in ΔF_{Tan} perfectly cancel the asymmetric contributions of F_{CCT} specifically in reduced-Ca²⁺ media. However, a simpler explanation is that ΔF_{Tan} and F_{CCT} are both close to zero under these conditions, in support of the initial assumption that F_{Tan} is uniform about the blastoderm margin.

The myosin inhibitor blebbistatin also decreases CCT as measured using laser microdissection (5). However, blebbistatin additionally reduces the rate of myosin flow toward the actin band, which results in a reduction in the force that drives epiboly (5). Consequently, blebbistatin likely decreases both CCT and F_{Tan} . We added 13.8 μ M blebbistatin to compressed embryos and quantified both the rate of epiboly and blastoderm reorientation, as before. We found that, as in reduced-Ca²⁺ media, $\Delta v \approx 0$ (Fig. 4 *B*). In addition, we noted that the addition of blebbistatin resulted in



FIGURE 4 Disrupting CCT eliminates differential blastoderm migration and eliminates axis realignment. (A) An asymmetric embryo grown in reduced, 62.5 μ M Ca²⁺ media. (i) The initial blastoderm mass defines the AV axis (red arrows). (ii) The location of blastopore closure and eventual AP axis (*blue arrows*) coincide with the initial AV axis (*red arrows*). (iii) The migration pattern of the blastoderm shows nearly uniform migration (red parallel lines) over the course of epiboly. Consequently, migration of the center of the blastoderm margin (magenta transverse line) lies very near the AV axis (dashed black line; cf. Fig. 1 C). (B) (i and ii) Quantification of the CCT force which is equivalent to the slope of the linear fit. The slope of the linear fit is statistically equivalent to 0 when CCT is disrupted by lowering Ca²⁺ to 62.5 μ M (*i*; E2(-), -4 ± 5 nm s⁻¹, R² - 0.005, *p*-value = 0.82) or by introducing 13.8 μ M blebbistatin (*ii*; Bleb, 3 \pm 5 nm s⁻¹, $R^2 - 0.003$, p-value = 0.56). (iii) $F_{\text{CCT}}/c_{\text{Drag}}$ is statistically significantly lower (***p < 0.001) in embryos grown in E2(-) media or with introduced blebbistatin compared to embryos grown in E2(+) media. Error bars represent the standard deviation of the slope of the fit as described in Fig. 3 C. (iv) Overall rates of epiboly in E2(+), E2(-), and E2 with 13.8 μ M blebbistatin. The overall rate of epiboly in E2(-) is statistically equivalent to that observed in E2(+), whereas introduction of blebbistatin severely delays epiboly. The rates of epiboly reflect the mean \pm SD of the average rate of epiboly over multiple embryos (16 for E2(+), 15 for E2(-), and 11 for Bleb). (See also Fig. S6, Movies S4 and S5, and Table S1 for more detailed fit parameters.)

severely delayed epiboly (Fig. 4 *B*), consistent with a role for actomyosin flow in generating force that contributes to F_{Tan} (5).

In summary, reduction of CCT with either reduced Ca²⁺ media or the addition of blebbistatin blocked blastoderm reorientation in a dose-dependent manner, and essentially abolished the positive correlation between Δv and $\Delta \cos \theta$ while maintaining an intercept that is close to zero (Figs. 4 and S6; Movies S4 and S5 and Table S1). Further, the spatially uniform rate of blastoderm migration observed under these conditions implies that F_{Tan} is close to uniform. These results collectively implicate CCT as

the principal mechanism responsible for blastoderm reorientation.

F_{CCT} is comparable in magnitude to F_{Tan}

While it is not experimentally feasible to directly measure either F_{Tan} or F_{CCT} , we can estimate their relative magnitudes. The overall rate of epiboly, $40 \pm 4 \text{ nm s}^{-1}$, provides an approximate measure of $F_{\text{Tan}}/c_{\text{Drag}}$. The slope of $\Delta v/$ $\Delta \cos\theta$ likewise yields $F_{\text{CCT}}/c_{\text{Drag}} = 23 \pm 6 \text{ nm s}^{-1}$ (Fig. 3 *C*). Thus, $F_{\text{Tan}}/c_{\text{Drag}}$ and $F_{\text{CCT}}/c_{\text{Drag}}$ are comparable in magnitude, strongly suggesting that CCT significantly affects cell movements during epiboly. This result is intuitively consistent with the observation that CCT visibly distorts the shape of the embryo during epiboly.

We used experimentally obtained values of $F_{\rm CCT}/c_{\rm Drag}$ to simulate blastoderm migration in shape-perturbed embryos grown either in E2 media, E2 with reduced Ca²⁺ (62.5 μ M), or E2 with blebbistatin (13.8 μ M) (Fig. 4). $F_{\rm CCT}/c_{\rm Drag}$ values of 23 nm s⁻¹ (normal E2 media) and 0 nm s⁻¹ (reduced Ca²⁺ or blebbistatin) correctly predict the location of the blastoderm edges for embryos of different geometries (Fig. S7 and Movies S4 and S5). The agreement between our simulation and experimental results under a range of mechanical and molecular perturbations reinforces the argument that reorientation is principally a function of CCT.

Extracellular calcium regulates coordinated cell migration at the blastoderm margin

We hypothesized that CCT, in addition to globally coordinating the blastoderm margin during epiboly, might coordinate the movement of neighboring cells. Previous results have shown that migrating epithelial sheets commonly exhibit finger-like protrusions caused by local variations in migration velocity (3). In contrast, the blastoderm margin maintains a smooth boundary throughout epiboly (Fig. 5 *A*). We therefore imaged the actin cytoskeleton of enveloping layer cells in fixed embryos between 55% and 60% epiboly using TMR-phalloidin. Reduced Ca²⁺ media (62.5 μ m) was used to selectively disrupt CCT (Fig. S2 and Movie S6). (Blebbistatin reduces both CCT and the tangential force, F_{Tan} , and would therefore be expected to decrease both the forces leading to (F_{Tan}) and resisting (F_{CCT}) the formation of instabilities.)

In embryos grown in normal E2, we observe that the cells form a smooth margin (Fig. 5 *A*). In contrast, embryos grown in reduced-Ca²⁺ media exhibit noticeably more disorder along the blastoderm margin (Fig. 5 *B*). We quantified the blastoderm margin roughness by measuring the correlation vector between adjacent cells (Figs. 5 *C* and S2). We use this metric as opposed to measuring the roughness of the membrane boundary to avoid quantifying instabilities influenced by cell morphology. Cell-cell vectors are more correlated for embryos grown in normal E2 versus E2



FIGURE 5 Reduction of CCT in E2(–) media reduces the coordination of neighboring cells at the blastoderm margin. (*A* and *B*) View of the blastoderm margin in TMR-phalloidin-stained embryos fixed at 60% epiboly after developing in E2(+) (*A*) or E2(–) (*B*). Cell-to-cell coordination is markedly reduced in low Ca²⁺ media. The apparent striations in (*A*) and (*B*) result from finite slice spacing in the confocal images (see also Fig. S2 and Movie S6). (*C*) The distribution of cell-cell correlation vectors shows a statistically significant increase in margin roughness for embryos grown in E2(–). *Red line*, mean; *box*, first and third quartiles; whiskers, 2.7 standard deviations. (*D*) Schematic of tension along the blastoderm margin. Tension (*blue arrows*) generates a net restorative force (*green arrow*) against local perturbations. Scale bars, 40 μ m.

with reduced Ca²⁺ (0.82 vs. 0.69; P < 0.01, Kolmogorov– Smirnov test). It is important to note that the variance in cell-cell angles is likewise lower for embryos grown in normal E2 versus reduced-Ca²⁺ E2 (0.040 vs. 0.082; P <0.0001, F-test). These observations show that the marginal cells in embryos grown in normal E2 are highly aligned, and that disruption of CCT via Ca²⁺ depletion corresponds to a decrease in cell-cell coordination. This increased misalignment supports the hypothesis that tension within the actin band coordinates cell migration throughout the blastoderm margin (Fig. 5 *D*).

The AP and AV axes are not synonymous in zebrafish

A question remains as to whether the mechanical forces generated by the actin band have an effect on overall zebrafish development, for example, in axis formation. Previous studies have reported that the AP axis forms along the AV axis, but it was unclear whether this is truly the case or whether the two axes are functionally distinct but overlapping (Fig. 2 I) (25-27). In compressed embryos grown in E2 media, we observe, for the first time to our knowledge, formation of the AP axis of the zebrafish, as indicated by the location of converging cells that form the head and tail (Fig. 2 E, blue arrows), which is decoupled from the initial AV axis (Fig. 2 E, red arrows). In these embryos, the AP axis shifts toward the imposed long axis of the embryo. To test whether the shift in AP axis was due to the symmetry of the embryo or instead resulted from nonuniform cell migration due to F_{CCT} , we monitored development in compressed embryos grown in reduced-Ca²⁺ media. We observe that under these conditions the posterior end forms near the site of the vegetal pole (Fig. 4 A). We therefore conclude that the AP axis is specified by the site of blastopore closure and is distinct from the AV axis.

DISCUSSION

Until recently, the prevailing hypothesis concerning the role of CCT was that it helped drive epiboly movements past 50% by constricting the blastoderm margin (8). However, a recent study suggested that actomyosin flow, independent of CCT, generates sufficient force to drive epiboly (5). This view of epiboly is supported by our observation that disruption of the actin band in low-Ca²⁺ media does not result in epibolic arrest. Previous experiments targeting CCT using chemical perturbations such as blebbistatin may have arrested epiboly not by eliminating CCT in its role as a supplementary force, but instead by inhibiting flow friction, an explanation supported by our observation that blebbistatin prevents epiboly from completing, whereas decreased Ca²⁺ does not (7,28,29).

Our data support a model in which tension within the actin band coordinates cell migration along the blastoderm margin on both global and local scales. Alternate mechanisms, for example, relocalization of actin and myosin to generate greater tangential force on one side of the embryo, could in principal drive reorientation. Additional factors such as cell adhesion (19,28), cell differentiation (8,17,18,30,31), and convergent extension movements (4,32) may also influence the rate and geometry of epiboly. However, a physical model based on CCT (Eq. 5) is sufficient to quantitatively account for the rate and extent of blastoderm reorientation under a broad range of experimental conditions. In the absence of additional data necessitating a more complex model, we thus prefer the minimalistic mechanism proposed here.

According to Eq. 5, tension within the actin band pulls unequally on the edges of the blastoderm of an asymmetric embryo, speeding the migration of the trailing edge and slowing the leading edge. In addition, CCT generates a restoring force against perturbations that might otherwise develop along the margin, thus preventing local instabilities analogous to the finger-like patterns observed during in vitro epithelial spreading (3). Decreasing the tension in the actin band either via low Ca²⁺ or added blebbistatin relaxes the CCT rubber band. As a result, both the leading and trailing sides of the blastoderm margin move at the same rates. Disruption of the actin band additionally results in spontaneous disorder among the marginal cells, again suggesting that CCT helps maintain cell-cell coordination. It is important to note that the force generated by CCT does not stall epiboly, since the experimentally determined maximal CCT contribution (23 ± 6 nm s⁻¹) is less than that of the overall epiboly rate (40 ± 4 nm s⁻¹).

A consequence of nonuniform blastoderm migration in asymmetric embryos is that the AP and AV axes are not equivalent, which has been a subject of discussion in understanding zebrafish axis specification (25,26). Our results support the hypothesis that the AP axis is established via migration patterns that determine the location of blastopore closure, a distinction that would be difficult to make in a symmetric embryo. Signals such as FGF and retinoic acid control the spatial expression of genes specifying anterior and posterior fates, and moreover coincide with the location of the blastoderm margin during epiboly (33). Recent results suggest in addition that the specification of the AP and dorsoventral (DV) axes are intimately coordinated, and occur in the same time frame as epiboly (34). Mechanical reorientation of the margin may thus lead to a redistribution of posteriorizing factors, providing an appealing mechanism that links mechanical and chemical patterning.

Little is currently known about how cell migration is coordinated across distances that are large relative to individual cells (35–39). Our study introduces a proposed role for CCT generated by the actin band in coordinating cell movements during epiboly. Analogous contractile actin bands are also observed during wound healing (9,10) and during dorsal closure in *Drosophila* embryos (11–13). We speculate that tension generated at the margin of cell sheets may thus provide a general means of coordinating cell movements in a wide variety of developmental and physiological processes. This link between mechanics and morphogenesis complements recent results demonstrating that mechanical signals can alter morphogenesis in both *Drosophila* and mouse embryos (35,36,40,41).

SUPPORTING MATERIAL

Supporting Materials and Methods, seven figures, one table, and six movies are available at http://www.biophysj.org/biophysj/supplemental/ S0006-3495(15)00410-5.

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Biophysical Journal

Supporting Material

A Force Balance Explains Local and Global Cell Movements during Early Zebrafish Development

Jack Chai,¹ Andrea L. Hamilton,² Michael Krieg,² Craig D. Buckley,¹ Ingmar H. Riedel-Kruse,³ and Alexander R. Dunn^{1,4,*}

¹Dept. of Chemical Engineering, Stanford University, ²Dept. of Molecular and Cellular Physiology,

Stanford School of Medicine, ³Dept. of Bioengineering, Stanford University, and ⁴Stanford

Cardiovascular Institute, Stanford University School of Medicine, Stanford, California 94305

3D modeling on an ellipsoid

General description of 3D modeling of epiboly

For the 3D model, we assume the same two forces as we did in the 2D model: F_{Tan} , the driving force of epiboly directed along the surface of the embryo, and F_{CCT} , the cable constriction tension generated by the actin band that is directed towards the center of the actin band. In the sections below, we describe how F_{Tan} and F_{CCT} may be reasonably defined, and how we defined these quantities in our analytical model and simulations.

Description of *F*_{Tan}

 F_{Tan} is defined along the surface of the embryo since all the processes of epiboly including microtubule polymerization and flow friction occur on the surface of the embryo. (1-7) We employ the simplifying assumptions the forces generated in F_{Tan} are uniform along each point of the margin and depends only on the current configuration of the embryo since, as shown below, more complex alternatives are not required to explain our observations.

Description of *F*_{CCT}

Prior evidence (2, 8, 9) suggests that the actin band exerts a line tension at the blastoderm margin that results in an inward-pointing force termed F_{CCT} . Multiple methods exist for modeling line tensions. One such possibility would be to represent the line tension by springs along the margin of the blastoderm. Another such possibility would be to scale the tension along the margin as inversely proportional to the local radius of curvature (Force is proportional to 1/r), similar to the pressure difference generated in a Young-Laplace law. In both models, the areas of highest curvature have the greatest force that is pointed towards the center of the ring: in the case of the springs, the springs are oriented more towards the center, and in the curvature example, the areas of lowest curvature are along the major axis (Figure S5). A consequence of these models is that the force is highest along the major axis and lowest along the minor axis and adopts intermediate force values in between these two points. In the sections below, we scale F_{CCT} by the distance of the point along the margin to the center of the band, which results in a similar results as the spring and curvature models. This approximation results in a tractable, analytical solution.

Setting the geometry of the embryo

In order to understand the effects of geometry on the actin band in 3D, we began by modeling the embryo as an ellipsoid centered at (0,0,0) in Cartesian coordinates:

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$
 (S1)

We will first solve the general case in which a, b and c are not equal. Later, we will show that the case in which a = b results in a simple linear solution. We designate the z-axis as the long axis such that c > a and c > b. Without loss of generality, we specify that the animal pole corresponds to a positive z-value.

We begin on this ellipsoid by defining the ring for the actin band, which can be expressed by intersecting a plane with the ellipsoid described in equation S1 (Figure S4A). If we make the *yz*-plane the equivalent of our experimental observation plane, we can assume that the ring will be symmetric with respect to the *yz*-plane. Consequently, we can define the intersection plane to be:

$$z = my + d \tag{S2}$$

The slope m defines the angle of the ring, such that any non-zero value creates an intersection plane that is asymmetric with respect to the ellipsoid. The intercept d represents the progress of epiboly. At the start of epiboly the ring is located more towards the animal pole and the intercept d has a positive value. As epiboly progresses d decreases. We obtain an equation for the ring by combining equations S1 and S2:

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{(my+d)^2}{c^2} = 1$$
(S3)

Defining *F*_{CCT}

As described in the in the sections above, *Fcct* points toward the center of the ring and is scaled by the distance from the center of the ring. To find the center of the ring we note that we have defined the ring symmetric as with respect to the *yz*-plane. Consequently, the center of the ring must be located at x = 0. Solving the set of equations in (S2) and (S3) when x = 0, we observe that the center of the ring (x',y',z') is located at:

$$x' = 0$$

$$y' = \frac{-mdb^2}{c^2 + m^2 b^2}$$

$$z' = \frac{dc^2}{c^2 + m^2 b^2}$$
(S4)

We can confirm that our solution for the ring center is correct through the following observations. When m = 0 we expect that the ring to be parallel to the *xy* plane centered along the *z*-axis (Figure S4B). When d = 0, we expect the ring to cut through the center of the ellipsoid. (Figure S4C).

We define the normalized vector for F_{CCT} at any arbitrary point (x_1, y_1, z_1) on the ring:

$$F_{CCT,x,norm} = \frac{-(x_1 - x')}{\left\|F_{CCT,norm}\right\|}$$
(S5a)

$$F_{CCT,y,norm} = \frac{-(y_1 - y')}{\left\|F_{CCT,norm}\right\|}$$
(S5b)

$$F_{CCT,z,norm} = \frac{-(z_1 - z')}{\left\|F_{CCT,norm}\right\|}$$
(S5c)

||CCT|| is a normalization factor that is defined as shown:

$$\left\|F_{CCT,norm}\right\| = \frac{2\int \sqrt{(F_{CCT,x,norm}^{2} + F_{CCT,y,norm}^{2} + F_{CCT,z,norm}^{2})} dy_{1}}{2\int dy_{1}}$$
(S6)

The integral is a line integral around the entire ring. The factor of 2 in both the numerator and denominator reflect the fact that each y_1 value has two corresponding x_1 value. Since the shape we are using is symmetric across the *yz*-plane, the positive and negative x_1 arcs have equal integrals. Consequently, the integral around the entire ring can be obtained by doubling the integral on an arc of a positive x_1 ring. Also, note that $||F_{CCT,norm}||$ is constant. The normalized vectors, as defined here, do not have magnitudes equal to 1, but instead maintain the scaling as defined by the distance to the ring center.

Defining F_{Tan}

Simple geometric observations show that the tangent vector must lie on two distinct planes. First, the tangent vector must exist on a surface tangent at the point on the ring $(x_1, y_1, z_1;$ Figure S4D). A tangent to the surface at this point can be found by finding the plane perpendicular to the surface normal as shown by defining a function:

$$f(x, y, z) = 1 - \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2}$$
(S8)

The surface normal is given by the gradient of *f* following a derivative of S8:

$$\bar{n}(x_1, y_1, z_1) = \nabla f \Big|_{x_1, y_1, z_1} = \left(\frac{2x_1}{a^2}, \frac{2y_1}{b^2}, \frac{2z_1}{c^2}\right)$$
(S9)

The surface normal is a vector which is by definition perpendicular to the surface of the ellipsoid. Since we know that F_{Tan} lies on the surface of the ellipsoid, we can find the plane that is perpendicular to the surface normal to find the plane on which F_{Tan} must lie. At the point (x_1,y_1,z_1) , this will generate the following equations for the tangent plane to the surface derived by taking find the perpendicular plane to equation S9:

$$\bar{n}(x_1, y_1, z_1) \bullet (x - x_1, y - y_1, z - z_1) = 0$$

$$\frac{2x_1}{a^2}(x - x_1) + \frac{2y_1}{b^2}(y - y_1) + \frac{2z_1}{c^2}(z - z_1) = 0$$
(S10)

Second, the tangent vector corresponding to F_{Tan} must also exist on the plane that contains the point on the ring, (x_1,y_1,z_1) ; the center of the ring, (x',y',z'); and the center of the ellipsoid, (0,0,0) (Figure S4D). This follows from the choice of coordinates: the center of the ring necessarily passes through (0,0,0) due to the initial choice of the *yz* plane. The plane determined by these three points can be defined as below:

$$\begin{vmatrix} x-0 & y-0 & z-0 \\ x'-0 & y'-0 & z'-0 \\ x_1-0 & y_1-0 & z_1-0 \end{vmatrix} = 0$$
(S11)
$$x(y'z_1-y_1z')-y(x'z_1-x_1z')+z(x'y_1-x_1y')=0$$

When we solve equations S10 and S11 simultaneously, we obtain

$$\alpha y - \beta z + \gamma = 0 \tag{S12}$$

Where

$$\alpha = \left(\frac{2x_1^2 z'}{a^2} - \frac{2y_1(y'z_1 - y_1 z')}{b^2}\right) = \frac{2d(c^2 - d^2)}{c^2 + m^2 b^2}$$
(S13)

$$\beta = \left(\frac{2x_1^2 y'}{a^2} + \frac{2z_1(y'z_1 - y_1 z')}{c^2}\right) = \frac{-2d(mb^2 + dy_1)}{c^2 + m^2 b^2}$$
(S14)

$$\gamma = \frac{2x_1^2}{a^2} y' z_1 - \frac{2x_1^2}{a^2} y_1 z' + \left(\frac{2y_1^2}{b^2} + \frac{2z_1^2}{c^2}\right) (y' z_1 - y_1 z')$$
(S15)

According to the definition of the coordinate system, movement along the tangent vectors will result in a negative progression along the *z*-axis. Consequently, for locations other than the poles, we differentiate with respect to negative movement in z to obtain the normalized tangent vectors. By differentiating equation S12 with respect to negative movement in z, we can obtain

the *y*-component of the tangent. Similarly, differentiating equation S10 yields the *x*-component of the tangent:

$$F_{Tan,x,norm} = \frac{-\frac{x_1\left(y'-z'\frac{\beta}{\alpha}\right)}{y'z_1-y_1z'}}{\|F_{Tan,norm}\|} = \frac{x_1(md^3b^2+d^2c^2y_1)}{\|F_{Tan,norm}\|}$$
(S16a)

$$F_{Tan,x,norm} = \frac{-\left(\frac{\beta}{\alpha}\right)}{\|F_{Tan,norm}\|} = \frac{\frac{mb^2+dy_1}{c^2-d^2}}{\|F_{Tan,norm}\|}$$
(S16b)

$$F_{Tan,z,norm} = \frac{-1}{\|F_{Tan,norm}\|}$$
(S16c)

In this form, $F_{Tan,norm}$ is defined to normalize the vector to unity and can be calculated by:

$$\left\|F_{Tan,norm}\right\| = \sqrt{\left(\frac{x_1\left(y'-z'\frac{\beta}{\alpha}\right)}{y'z_1 - y_1z'}\right)^2 + \left(\frac{\beta}{\alpha}\right)^2 + (-1)^2}$$
(S17)

Simulating epiboly progression

Having obtained all components of the tangent vector and the CCT vector, we can find the angle θ as a function of position on the ring:

$$\cos(\theta) = \bar{F}_{CCT,norm} \bullet \bar{F}_{Tan,norm} = \frac{-\frac{a^2 \beta}{b^2 \alpha} y_1 + \frac{\beta}{\alpha} y_1 + \left(\frac{mdb^2}{c^2 + m^2 b^2}\right) \frac{\beta}{\alpha} - \frac{a^2}{c^2} z_1 + z_1 - \frac{dc^2}{c^2 + m^2 b^2}}{\|F_{Tan,norm}\|}$$
(S18a)

If we assume symmetry around the *z*-axis (a = b) and substitute in Equation S2 we obtain:

$$\cos(\theta) = \vec{F}_{CCT,norm} \bullet \vec{F}_{Tan,norm} = \frac{\left(\frac{mdb^2}{c^2 + m^2b^2}\right) \left(\frac{mb^2 + dy_1}{c^2 - d^2}\right) + \left(1 - \frac{b^2}{c^2}\right) (my_1 + d) - \frac{dc^2}{c^2 + m^2b^2}}{\|F_{Tan,norm}\|\|F_{CCT,norm}\|}$$
(S18b)

From this we observe that the correlation between the CCT and tangent vectors are linear with respect to movement in *y* in the *yz*-plane, which is consistent with our presentation of the 2D model. If we model embryo development using experimentally determined values of F_{CCT} and F_{Tan} (Figure S4E-G), we see that in a spherical embryo (a = b = c), the migration pattern of this ring is uniform around the sphere (Figure S4E and Movie S2). If the initial blastoderm mass is symmetric with respect to the *z*-axis (m = 0) the blastoderm likewise migrates uniformly, as would be expected (Figure S4F and Movie S3). However, if we place the initial ring in an asymmetric location, the blastoderm migrates unevenly and rotates to be symmetric along the long axis, as was observed experimentally (Figure S4G and Movie S4).



Figure S1: *Left:* Image of a compressed zebrafish embryo. Right: boundary determination using a Canny-Deriche edge detection algorithm.



Figure S2: Quantification of cell-cell correlation at the blastoderm margin in a uncompressed embryo grown in normal E2 media. *Left*: Image of a TMR-phalloidin stained embryo. *Right*: The outlines of the cells at the margin were determined manually. Blue outlines show the cell boundary. The green dots indicate the calculated center of the cell.



Figure S3: Examples of different shapes adopted by embryos under agar compression. Compression can induce highly asymmetrical shapes as seen in the left and middle panels. Compression can also induce minor deviations from axial symmetry without an apparent long axis (right panel). Scale bar = $250 \mu m$.



Figure S4: 3D models of CCT. (A) The blastoderm margin can be modeled as a ring obtained by intersecting a plane with the yolk ellipsoid. (B) Any intersection of a plane of positive slope and intercept in the *yz*-plane results in a ring that has a center that lies along the y-axis (x = 0) with a negative y-coordinate (y < 0).e. (C) Any plane that cuts through the origin will have a center at the origin. (D) As predicted, a level plane creates a symmetric ring around the z-axis with a constant center at x = 0 and y = 0. (E) A tangential vector (black vector) to a point on the ellipsoid can be calculated by intersecting the plane tangent to the surface at that point (blue plane) with a plane that is defined by the point on the surface, the center of the ring, and the center of the ellipsoid (pink plane with points indicated by purple dots). (F) In the asymmetric embryo, we see that the 3D evolution of the ring exhibits differential migration as time progresses (indicated by the darkening of the blue lines). (G-H) Control models of the embryo show uniform migration on a symmetric ellipsoid (G) as well as for a spherical yolk (H).



Figure S5: Description of *Fcct* on an ellipse. (A) In a general ellipse, we will look at the areas corresponding to the minor axis (i) and major axis (ii) and observe the magnitude of *Fcct* using the spring model and curvature model. (B) Magnitude of *Fcct* using the spring model. (i) *Fcct* at the minor axis using the spring model. (*Top*) At the point along the minor axis of the ellipse, the spring pulls equally on the left (green) and right (red) side. (*Bottom*) Most of the force of the springs is projected perpendicularly to the direction of *Fcct* (green and red) which results in a small total *Fcct* (blue). (ii) *Fcct* at the major axis of the embryo, the spring pulls equally above (green) and below (red) the point. (*right*) Due to the high curvature, the spring forces (green and red) are more directed towards the center of the ring leading to high overall *Fcct*. (C) Magnitude of *Fcct* using the curvature model. (i) At the minor axis point, the radius of curvature, as determined by the radius of circle that is tangent to that point (*rminor*, green), is large. Since *Fcct* is inversely proportional to *rminor*, *left*, *green*) is small, *Fcct* is large. In both the spring and curvature model, *Fcct* is small at the minor axis and large at the major axis.



Figure S6: Dose dependence of chemical treatments that affect the basal rate of epiboly. (A) F_{CCT}/c_{Drag} as a function of media Ca²⁺ concentration. (B) F_{CCT}/c_{Drag} as a function of blebbistatin concentration. Both treatments block blastoderm margin reorientation in a dose-dependent manner. (C) Basal rates of epiboly in multiple embryos grown in different conditions were calculated by averaging the rate of the left and right edge of the margin at different time points. The basal epiboly rate is statistically identical for embryos grown in E2 (E2(+)) and in reduced Ca2+ (E2(-); 62.5 μ M; P = 0.70). However, when blebbistatin is introduced, the basal epiboly rate is decreased significantly. (P < 0.0001). The error bars represent standard error.



Figure S7: An analytic model recapitulates local variations in blastoderm migration over 3 hours in asymmetric embryos. Blue lines indicate the predicted blastoderm edges using a model that incorporates a CCT force component. Red lines indicate the predicted edges for a model lacking a contribution from CCT. For an embryo grown in normal E2 (E2(+); *top row*, A-E) the model that includes CCT (blue lines) predicts the location of the blastoderm edges whereas a model lacking CCT does not (red lines). Embryos grown in reduced Ca²⁺ (62.5 μ M) E2 (E2 (-); *middle row*, F-J) or E2 plus 13.8 μ M blebbistatin (Bleb; *bottom row*, K-O) are better predicted by a model that does not incorporate CCT (red lines). (D, I, N) Zoomed in images of the left edge of the blastoderm margin. (E, J, O) Zoomed in images of the right edge of the blastoderm margin. (Scale bar = 250 μ m)

		Slopo		Intercent	n voluo
		Slope	p-value	Intercept	p-value
Condition	n	(nm/s)	(Slope = 0)	(nm/s)	(Intercept = 0)
Normal E2 (1mM Ca ²⁺)					
(E2(+))	16	23 ±6	0.0001	0.30±1.56	0.84
E2 + 0.25 mM Ca ²⁺	11	18 ±6	0.003	-1.58±1.42	0.27
E2 + 0.125 mM Ca ²⁺	10	7 ±7	0.38	-2.10±1.74	0.23
E2 + 0.0625 mM Ca ²⁺					
(E2(-))	15	-4 ±5	0.82	4.26 ±1.50	0.005
E2 + 4.6 µM Blebbistatin	14	18 ±5	0.001	2.75±1.82	0.13
E2 + 13.8 µM					
Blebbistatin (Bleb)	11	3 ±5	0.56	2.22 ±1.75	0.21

Table 1: Linear fits of Δv vs $\Delta \cos \theta$ in compressed embryos have *y*-axis intercepts that are close to zero and slope values that vary depending on Ca²⁺ and blebbistatin concentration, suggesting differences in *F*_{CCT} (cf. Figure 3C, 4B, S2). These results agree with the control case of uncompressed embryos in which uniform blastoderm migration is observed. According to Equation 4, the plot of Δv vs $\Delta \cos \theta$ should have a slope that corresponds to *F*_{CCT}/*c*_{Drag} and an intercept that corresponds to $\Delta F_{Tan}/c_{Drag}$. The observation that the intercept is close to 0 in all cases supports the hypothesis that tangential forces are uniform and that ΔF_{Tan} can assumed to be 0. **Movie S1**: Related to Figure 2. Movie of a compressed embryo grown in E2 media. Blue lines indicate the predicted edges of the blastoderm margin using a model incorporating F_{CCT}/c_{Drag} value of 28 nm s⁻¹. Red lines indicate the predicted edges of the blastoderm margin using a model without incorporating CCT. Over the course of epiboly, the model that incorporates CCT (blue) better predicts the position of the blastoderm margin.

Movie S2: Related to Figure 3. Movie showing the progression of epiboly on a 3D asymmetric ellipsoid. (Left) At each marginal ring, a uniform tangential force (red) is generated around the ring directed along the tangent of the ellipsoid while a force due to CCT (green) is generated around the ring and points toward its center. (Middle) Due to the uneven contribution of CCT (green), on the left side CCT projects negatively onto the tangent while on the right side CCT projects positively onto the tangent. Combining this with the uniform tangential force results in uneven net tangential forces (Right, maroon). Consequently, the right side of the ring progresses faster than the left side, resulting in reorientation of the ring perpendicular to the long axis of the ellipsoid.

Movie S3: Related to Figure 3. Movie showing the progression of epiboly on a 3D ellipsoid with a symmetric ring (top) and on a sphere (bottom). (Left) CCT (green) produces a uniform force around the ring along with a uniform tangent force (red). Since the ring is symmetric, CCT provides an equal contribution of force to the tangent at each point on the ring resulting in a uniform net tangential force (right, maroon). Consequently, the ring progresses uniformly down both the ellipsoid and the sphere.

Movie S4: Related to Figure 4. Movie showing a compressed embryo grown in reduced Ca²⁺ (62.5 μ M) media. Blue lines indicate the predicted edges of epiboly using a model incorporating a F_{CCT}/c_{Drag} value of 28 nm s⁻¹. Red lines indicate the predicted edges of epiboly using a model without incorporating CCT. Over the course of epiboly, the model that lacks CCT (red) better predicts the position of the blastoderm margin edges.

Movie S5: Related to Figure 4. Movie showing a compressed embryo grown in media with 13.8 µM blebbistatin. Blue lines indicate the predicted edges of epiboly using a model that incorporates a F_{CCT}/c_{Drag} value of 28 nm s⁻¹. Red lines indicate the predicted edges of epiboly using a model without incorporating CCT. Over the course of epiboly, the model that lacks CCT (red) better predicts the position of the blastoderm margin edges.

Movie S6: Related to Figure 5. Movie of a compressed embryo grown in normal E2 (left) and in reduced Ca^{2+} (62.5 μ M, right) media over 18.6 hours. In both cases, the embryos develop properly through the conclusion of epiboly.

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